

# Machine Learning

## 18 – VC Dimensions, Support Vector Machines (1)

November 17, 2022

## PAC Learning

**Theorem (Valiant, 1984):** If the hypothesis space  $H$  is finite, and  $D$  is a sequence of  $n \geq 1$  independent random examples of some target concept  $c$ , then for any  $0 \leq \varepsilon \leq 1$ , the probability that  $VS_{H,D}$  contains a hypothesis with error greater than  $\varepsilon$  is less than  $|H|e^{-\varepsilon n}$ , i.e.,

$$Pr[Err > \varepsilon] < |H|e^{-\varepsilon n}$$

Let us want this probability to be at most  $\delta$ , i.e.,

$$|H|e^{-\varepsilon n} \leq \delta$$

Then,

$$n \geq \frac{1}{\varepsilon}(\ln |H| + \ln(1/\delta))$$

1. With linear increase in data, the bound becomes exponentially better.
2.  $|H|$  can be large, requiring more data (If  $|H|$  is infinity, the bound does not help).

## PAC Learning

**Theorem (Valiant, 1984):** If the hypothesis space  $H$  is finite, and  $D$  is a sequence of  $n \geq 1$  independent random examples of some target concept  $c$ , then for any  $0 \leq \varepsilon \leq 1$ , the probability that  $VS_{H,D}$  contains a hypothesis with error greater than  $\varepsilon$  is less than  $|H|e^{-\varepsilon n}$ , i.e.,

$$Pr[Err > \varepsilon] < |H|e^{-\varepsilon n}$$

Let us want this probability to be at most  $\delta$ , i.e.,

$$|H|e^{-\varepsilon n} \leq \delta$$

Then,

$$n \geq \frac{1}{\varepsilon}(\ln |H| + \ln(1/\delta))$$

1. With linear increase in data, the bound becomes exponentially better.
2.  $|H|$  can be large, requiring more data (If  $|H|$  is infinity, the bound does not help). **[What can we do if  $|H|$  is infinity?]**

## VC Dimensions

**Dichotomy:** A dichotomy of a set  $S$  is a partition of  $S$  into two disjoint subsets.

## VC Dimensions

**Dichotomy:** A dichotomy of a set  $S$  is a partition of  $S$  into two disjoint subsets.

**Shattering:** A set of instances  $S$  is said to be *shattered* by a hypothesis space  $H$  iff for every dichotomy of  $S$ , there exists some hypothesis in  $H$  consistent with this dichotomy.

## VC Dimensions

**Dichotomy:** A dichotomy of a set  $S$  is a partition of  $S$  into two disjoint subsets.

**Shattering:** A set of instances  $S$  is said to be *shattered* by a hypothesis space  $H$  iff for every dichotomy of  $S$ , there exists some hypothesis in  $H$  consistent with this dichotomy.



Figure: Shattering a set  $S$  with  $|S| = 3$  by a set of hypotheses of straight lines.

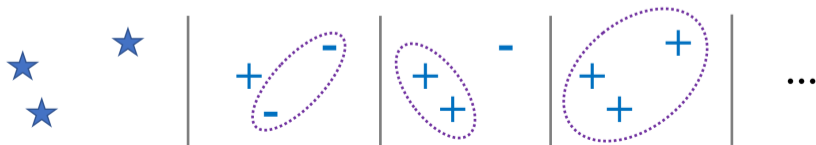


Figure: Shattering a set  $S$  with  $|S| = 3$  by a set of hypotheses of ellipses.

## VC Dimensions

**Dichotomy:** A dichotomy of a set  $S$  is a partition of  $S$  into two disjoint subsets.

**Shattering:** A set of instances  $S$  is said to be *shattered* by a hypothesis space  $H$  iff for every dichotomy of  $S$ , there exists some hypothesis in  $H$  consistent with this dichotomy.

**Vapnik-Chervonenkis Dimension (1971):**  $VC(H)$  of a hypothesis space  $H$  defined over instance space  $X$  is the size of the largest finite subset of  $X$  shattered by  $H$ .

If arbitrary large finite sets of  $X$  can be shattered by  $H$ , then  $VC(H) \equiv \infty$ .

## VC Dimensions

**Dichotomy:** A dichotomy of a set  $S$  is a partition of  $S$  into two disjoint subsets.

**Shattering:** A set of instances  $S$  is said to be *shattered* by a hypothesis space  $H$  iff for every dichotomy of  $S$ , there exists some hypothesis in  $H$  consistent with this dichotomy.

**Vapnik-Chervonenkis Dimension (1971):**  $VC(H)$  of a hypothesis space  $H$  defined over instance space  $X$  is the size of the largest finite subset of  $X$  shattered by  $H$ .

If arbitrary large finite sets of  $X$  can be shattered by  $H$ , then  $VC(H) \equiv \infty$ .



Figure: 1. Shattering  $\mathbb{R}^2$  with  $n = 3$  by a set of hypotheses of straight lines.



## VC Dimensions

**Dichotomy:** A dichotomy of a set  $S$  is a partition of  $S$  into two disjoint subsets.

**Shattering:** A set of instances  $S$  is said to be *shattered* by a hypothesis space  $H$  iff for every dichotomy of  $S$ , there exists some hypothesis in  $H$  consistent with this dichotomy.

**Vapnik-Chervonenkis Dimension (1971):**  $VC(H)$  of a hypothesis space  $H$  defined over instance space  $X$  is the size of the largest finite subset of  $X$  shattered by  $H$ .

If arbitrary large finite sets of  $X$  can be shattered by  $H$ , then  $VC(H) \equiv \infty$ .

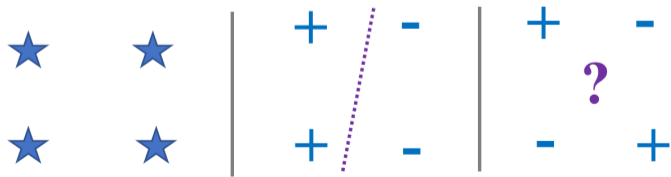


Figure: 2.  $\mathbb{R}^2$  with  $n = 4$  cannot be shattered by a set of hypotheses of straight lines.

## VC Dimensions

**Dichotomy:** A dichotomy of a set  $S$  is a partition of  $S$  into two disjoint subsets.

**Shattering:** A set of instances  $S$  is said to be *shattered* by a hypothesis space  $H$  iff for every dichotomy of  $S$ , there exists some hypothesis in  $H$  consistent with this dichotomy.

**Vapnik-Chervonenkis Dimension (1971):**  $VC(H)$  of a hypothesis space  $H$  defined over instance space  $X$  is the size of the largest finite subset of  $X$  shattered by  $H$ .

If arbitrary large finite sets of  $X$  can be shattered by  $H$ , then  $VC(H) \equiv \infty$ .

---

For  $\mathbb{R}^2$  and a hypothesis set  $H$  of straight lines:

- ▶  $n = 1$  is shattered by  $H$ .
- ▶  $n = 2$  is shattered by  $H$ .
- ▶  $n = 3$  is shattered by  $H$ .
- ▶  $n = 4$  is **not** shattered by  $H$ .

Hence  $VC(H) = 3$ .

## VC Dimensions

**Dichotomy:** A dichotomy of a set  $S$  is a partition of  $S$  into two disjoint subsets.

**Shattering:** A set of instances  $S$  is said to be *shattered* by a hypothesis space  $H$  iff for every dichotomy of  $S$ , there exists some hypothesis in  $H$  consistent with this dichotomy.

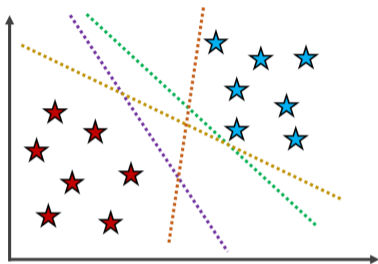
**Vapnik-Chervonenkis Dimension (1971):**  $VC(H)$  of a hypothesis space  $H$  defined over instance space  $X$  is the size of the largest finite subset of  $X$  shattered by  $H$ .

**Sample Complexity from VC Dimension (2000):** The number of randomly drawn examples that suffice to guarantee error of at most  $\varepsilon$  with probability at least  $(1 - \delta)$  is:

$$n \geq \frac{1}{\varepsilon} (8 VC(H) \ln(13/\varepsilon) + 4 \ln(2\delta))$$

# Support Vector Machines

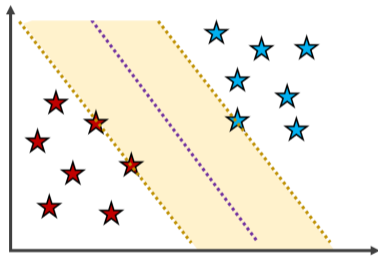
## Classification Hyperplanes



- ▶ Given sample instances from two linearly separable classes, there is an infinite number of hyperplanes that can correctly classify the samples.
- ▶ Can we create a definition of an *ideal* hyperplane?

## Maximum-Margin Hyperplanes

An *ideal* hyperplane: A hyperplane that has the **maximum margin** between the two classes.

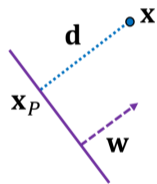


How can we define the margin of a hyperplane?

## Maximum-Margin Hyperplanes

Notations: For a binary classification problem, we have samples  $(\mathbf{x}^{(1)}, y^{(1)}), \dots, (\mathbf{x}^{(n)}, y^{(n)})$ ,  $\mathbf{x}^{(i)} \in \mathbb{R}^d$ ,  $y^{(i)} \in \{1, -1\}$ .

We wish to find a hyperplane  $\mathbf{w}^T \mathbf{x} + b = 0$  that has maximum margin, and correctly classifies the data.



We can define the distance vector  $\mathbf{d}$  of any instance  $\mathbf{x}$  to a hyperplane.

The normal to the hyperplane is  $\mathbf{w}$ , hence  $\mathbf{d} = \alpha \mathbf{w}$ .

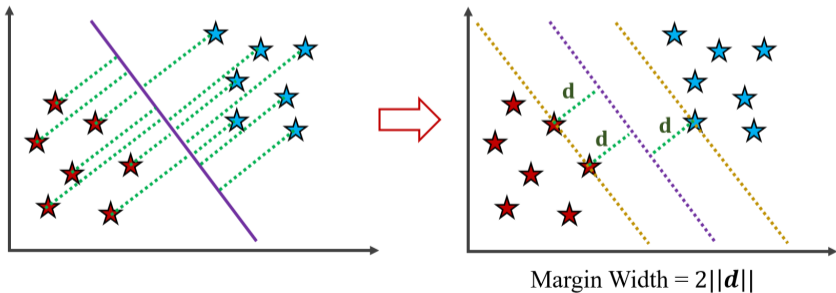
Let the projection of  $\mathbf{x}$  on to the hyperplane be  $\mathbf{x}_P$ , therefore  $\mathbf{x}_P = \mathbf{x} - \mathbf{d}$ . Then we can solve for  $\alpha$ ,

$$\begin{aligned}\mathbf{w}^T \mathbf{x}_P + b &= 0 \\ \implies \mathbf{w}^T (\mathbf{x} - \mathbf{d}) + b &= 0 \\ \implies \mathbf{w}^T (\mathbf{x} - \alpha \mathbf{w}) + b &= 0 \\ \implies \alpha &= \frac{\mathbf{w}^T \mathbf{x} + b}{\mathbf{w}^T \mathbf{w}}\end{aligned}$$

## Maximum-Margin Hyperplanes

For any  $\mathbf{x}$ , the distance vector to a hyperplane vector  $\mathbf{d} = \alpha \mathbf{w}$ ,  $\alpha = \frac{\mathbf{w}^T \mathbf{x} + b}{\mathbf{w}^T \mathbf{w}}$

Since we are interested in finding the *maximum* margin hyperplane, we can try to find the instances that are *nearest* to the hyperplane. The norm of their distance vectors will provide a measure of the margin width.





## Maximum-Margin Hyperplanes

For any  $\mathbf{x}$ , the distance vector to a hyperplane vector  $\mathbf{d} = \alpha\mathbf{w}$ ,  $\alpha = \frac{\mathbf{w}^T\mathbf{x} + b}{\mathbf{w}^T\mathbf{w}}$

$$\begin{aligned}\|\mathbf{d}\|_2 &= \sqrt{\mathbf{d}^T\mathbf{d}} = \sqrt{\alpha^2\mathbf{w}^T\mathbf{w}} \\ &= \frac{|\mathbf{w}^T\mathbf{x} + b|}{\sqrt{\mathbf{w}^T\mathbf{w}}} = \frac{|\mathbf{w}^T\mathbf{x} + b|}{\|\mathbf{w}\|_2}\end{aligned}$$

The margin  $\gamma$  is then defined as,

$$\gamma(\mathbf{w}, b) = \min_{\mathbf{x}} \frac{2|\mathbf{w}^T\mathbf{x} + b|}{\|\mathbf{w}\|_2}$$

Note that by this definition, the margin is scale invariant:

$$\gamma(\beta\mathbf{w}, \beta b) = \gamma(\mathbf{w}, b), \quad \forall \beta \neq 0$$

## Maximum-Margin Hyperplanes

Finding the maximum margin hyperplane can be posed as an optimization problem,

$$\max_{\mathbf{w}, b} \gamma(\mathbf{w}, b) \quad \text{s.t.} \quad y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 0 \quad \forall i$$

Note that since  $y^{(i)} \in \{1, -1\}$ , an accurate classifier will have:

$$y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 0 \quad \forall i.$$

## Maximum-Margin Hyperplanes

Finding the maximum margin hyperplane can be posed as an optimization problem,

$$\max_{\mathbf{w}, b} \gamma(\mathbf{w}, b) \quad \text{s.t.} \quad y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 0 \quad \forall i$$

Equivalently, the objective is,

$$\max_{\mathbf{w}, b} \left\{ \frac{2}{\|\mathbf{w}\|_2} \min_{\mathbf{x}^{(i)}} |\mathbf{w}^T \mathbf{x}^{(i)} + b| \right\} \quad \text{s.t.} \quad y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 0 \quad \forall i$$

We impose the constraint that  $\min_{\mathbf{x}} |\mathbf{w}^T \mathbf{x} + b| = 1$  to prevent an arbitrary large solution. Then the optimization objective is,

$$\begin{aligned} \max_{\mathbf{w}, b} \frac{2}{\|\mathbf{w}\|_2} \cdot 1 &= \min_{\mathbf{w}, b} \|\mathbf{w}\|_2 = \min_{\mathbf{w}, b} \mathbf{w}^T \mathbf{w} \\ \text{s.t.}, \quad y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) &\geq 0 \quad \forall i, \\ \min_i |\mathbf{w}^T \mathbf{x}_i + b| &= 1. \end{aligned}$$

## Support Vector Machines

The optimization objective:

$$\begin{aligned} \max_{\mathbf{w}, b} \frac{2}{\|\mathbf{w}\|_2} \cdot 1 &= \min_{\mathbf{w}, b} \|\mathbf{w}\|_2 = \min_{\mathbf{w}, b} \mathbf{w}^T \mathbf{w} \\ \text{s.t., } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) &\geq 0 \quad \forall i, \\ \min_i |\mathbf{w}^T \mathbf{x}^{(i)} + b| &= 1. \end{aligned}$$

Combining the constraints, we get an objective function for the classifier called Support Vector Machines:

$$\begin{aligned} \min_{\mathbf{w}, b} \mathbf{w}^T \mathbf{w} \\ \text{s.t., } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) &\geq 1 \quad \forall i. \end{aligned}$$

## Support Vector Machines

The optimization objective:

$$\begin{aligned} \max_{\mathbf{w}, b} \frac{2}{\|\mathbf{w}\|_2} \cdot 1 &= \min_{\mathbf{w}, b} \|\mathbf{w}\|_2 = \min_{\mathbf{w}, b} \mathbf{w}^T \mathbf{w} \\ \text{s.t.}, y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) &\geq 0 \quad \forall i, \\ \min_i |\mathbf{w}^T \mathbf{x}^{(i)} + b| &= 1. \end{aligned}$$

Combining the constraints, we get an objective function for the classifier called Support Vector Machines:

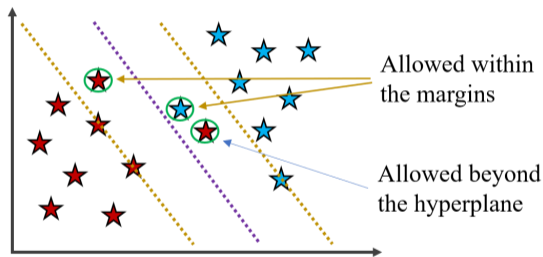
$$\begin{aligned} \min_{\mathbf{w}, b} \mathbf{w}^T \mathbf{w} \\ \text{s.t.}, y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) &\geq 1 \quad \forall i. \end{aligned}$$

Quadratic Optimization Problem (QOP): An optimization problem with a quadratic objective and with linear equality or linear inequality constraints. Quadratic solvers can solve QOPs (but they are not very efficient).

## Support Vector Machines with soft constraints

Our initial assumptions: Classes are linearly separable.

What if the classes are not linearly separable? We can find a maximum margin classifier that allows some misclassification.



Slack variables  $\xi^{(i)}$  are imposed to allow instances to cross the margin:

$$y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 1 - \xi^{(i)} \quad \forall i$$

## Support Vector Machines with soft constraints

Soft SVM Objective:

$$\begin{aligned} \min_{\mathbf{w}, b} \quad & \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^n \xi^{(i)} \\ \text{s.t.}, \quad & y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 1 - \xi^{(i)} \quad \forall i, \\ & \xi^{(i)} \geq 0 \quad \forall i. \end{aligned}$$

$C$  controls how strict SVM is to get all points on the correct side of the hyperplane. For larger  $C$ , SVM will try to be very accurate. For smaller  $C$ , SVM will allow more points to be on the incorrect side of the hyperplane.

## Support Vector Machines with soft constraints

Soft SVM Objective:

$$\begin{aligned} \min_{\mathbf{w}, b} \quad & \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^n \xi^{(i)} \\ \text{s.t.}, \quad & y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 1 - \xi^{(i)} \quad \forall i, \\ & \xi^{(i)} \geq 0 \quad \forall i. \end{aligned}$$

For points that satisfy the constraint  $y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 1$ , setting  $\xi^{(i)} = 0$  minimizes the objective.

Only for  $y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) < 1$ , do we need to set a proper  $\xi^{(i)} > 0$  so that the constraint  $y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 1 - \xi^{(i)}$  is satisfied. The minimum value of  $\xi^{(i)}$  that satisfies the constraint is then,

$$\xi^{(i)} = \begin{cases} 1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) & , \text{ if } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) < 1 \\ 0 & , \text{ if } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 1 \end{cases}$$



## Support Vector Machines with soft constraints

Soft SVM Objective:

$$\begin{aligned} \min_{\mathbf{w}, b} \quad & \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^n \xi^{(i)} \\ \text{s.t.}, \quad & y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 1 - \xi^{(i)} \quad \forall i, \\ & \xi^{(i)} \geq 0 \quad \forall i. \end{aligned}$$

A solution for  $\xi^{(i)}$ ,

$$\xi^{(i)} = \begin{cases} 1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) & , \text{ if } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) < 1 \\ 0 & , \text{ if } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 1 \end{cases}$$

Equivalently,

$$\xi^{(i)} = \max(1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b), 0)$$

## Support Vector Machines with soft constraints

Soft SVM Objective:

$$\begin{aligned} \min_{\mathbf{w}, b} \quad & \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^n \xi^{(i)} \\ \text{s.t.}, \quad & y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 1 - \xi^{(i)} \quad \forall i, \\ & \xi^{(i)} \geq 0 \quad \forall i. \end{aligned}$$

A solution for  $\xi^{(i)}$ ,

$$\xi^{(i)} = \max(1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b), 0)$$

A combined objective for SVM with Soft Constraints:

$$\min_{\mathbf{w}, b} \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^n \max [1 - y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b), 0]$$

## Support Vector Machines with soft constraints

Soft SVM Objective:

$$\min_{\mathbf{w}, b} \underbrace{\mathbf{w}^T \mathbf{w}}_{\ell_2 \text{ regularizer}} + C \sum_{i=1}^n \underbrace{\max [1 - y^{(i)} (\mathbf{w}^T \mathbf{x}^{(i)} + b), 0]}_{\text{Hinge Loss}}$$

This is similar to a Logistic Regression objective function with an  $\ell_2$  penalty.

## References

(Classification Validation) [1] Mohammed J. Z. and Wagner M. (2020). Data Mining and Machine Learning: Fundamental Concepts and Algorithms, Second Edition. Cambridge University Press.

(No Free Lunch Theorem) [2] Duda R. O., Hart P.E., Stork D. G. (2000). Chapter 9 - 9.2. No Free Lunch Theorem. Pattern Classification, 2nd Edition.

(PAC Learning) [3] Valiant L. (1984). "A theory of the learnable". Communications of the ACM. 27 (11): 1134-1142.

(VC Dimensions) [4] Vapnik V. N. and Chervonenkis A. Y. (1971). "On the Uniform Convergence of Relative Frequencies of Events to Their Probabilities". Theory of Probability & Its Applications. 16 (2): 264.

(VC Dimensions) [5] Vapnik V. N. (2000). The Nature of Statistical Learning Theory. Springer.

(Agnostic Learning) [6] Ali Ghodsi, Lec 19: PAC Learning. URL:  
<https://www.youtube.com/watch?v=q0MOYMOWCzU>.

(SVM) [7] Kilian Q. Weinberger, CS4780/CS5780 Lecture 9. URL:  
<https://www.cs.cornell.edu/courses/cs4780/2018fa/lectures/lecturenote09.html>

(SVM) [8] Andrew Ng, CS229 Support Vector Machines. URL:  
<https://see.stanford.edu/materials/aimlcs229/cs229-notes3.pdf>